

COLT tries to explain why and when machine learning works.

It studies two aspects of machine learning to provide insights for the design of learning algorithms.

- *Statistical*: how much data is needed to learn good models?
- *Algorithmic*: how computationally hard is it to learn such models?

COLT usually assumes a simple learning scenario called *concept learning*, which is (roughly) noise-free binary classification learning.

More complex scenarios often have concept learning at their heart.

Concept Learning Elements

- *Instance space*: a set X . Elements $x \in X$ are *instances*.
- *Concept*: a subset $C \subseteq X$.

The algorithm should learn to decide whether $x \in C$ for any given $x \in X$.

Example: X = animals described as tuples of binary variables

$$\begin{array}{rcccc} & \text{aquatic} & \text{airborne} & \text{backbone} & \\ \hline x = & 0 & 1 & 0 & \end{array}$$

C = all mammals.

- *Learning examples*: the learner must get some instances $x \in X$ with the information whether $x \in C$ or not.

To decide $x \in C$ for any given $x \in X$, the learner must be able to *compute* C , i.e., the function

$$c(x) = \begin{cases} 1 & \text{if } x \in C \\ 0 & \text{if } x \notin C \end{cases}$$

- *Countable* number of computable concepts (any algorithm has a finite description so their number is countable)
- But *uncountable* number of concepts if X infinite, e.g. $X = N$
- \rightarrow Non-computable concepts exist.

COLT studies the behavior of learners with respect to selected subsets $C \subset 2^X$ called *concept classes*.

Hypothesis Class

A finite description of a learner's decision model is called a *hypothesis*. Learners use constrained languages (rules, polynomials, graphs, ...) to encode their hypotheses.

For example, the hypothesis

$$\text{man} \wedge \overline{\text{married}}$$

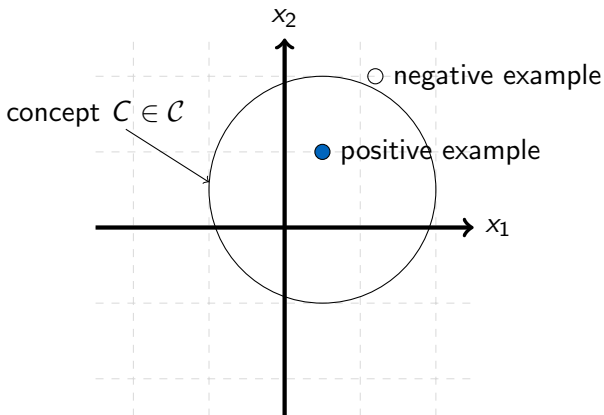
which is a *logical conjunction* defines the 'bachelor' concept.

Hypothesis languages are typically not Turing-complete so not all computable concepts can be expressed by hypotheses.

The set of all hypotheses a learner can express is called its *hypothesis class*.

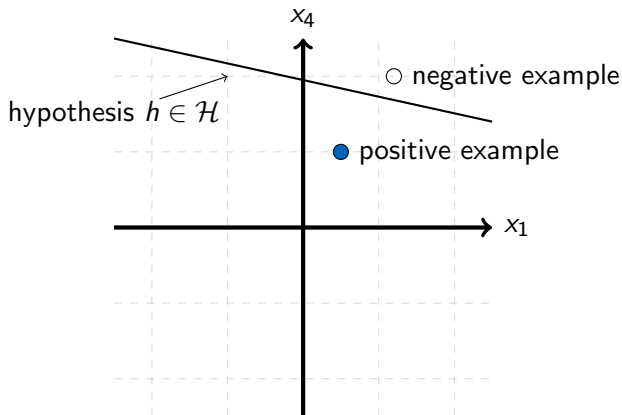
A Continuous-Domain Example

- Instance space $X = \mathbb{R}^2$
- Possible concept class \mathcal{C} : disks $(x_1 - a)^2 + (x_2 - b)^2 < r$



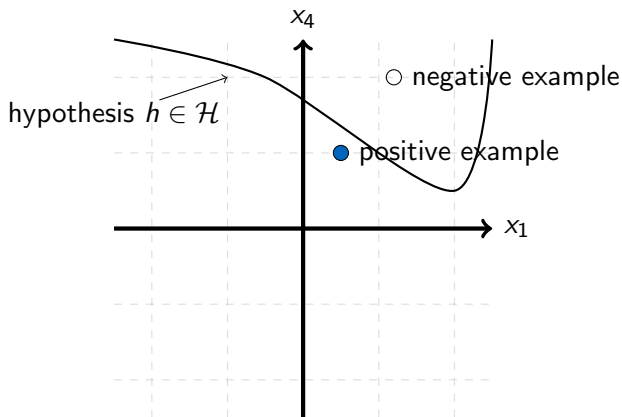
A Continuous-Domain Example (cont'd)

- Possible hypothesis class \mathcal{H} : half-planes $x_2 - ax_1 > b$
- Hypothesis description: (a, b) (with finite precision number repr.)



A Continuous-Domain Example (cont'd)

- Possible hypothesis class \mathcal{H} : neural networks
- Hypothesis description: graph + weights



Continuous vs. Discrete

Instances and hypotheses in continuous domains are largely the topic of a parallel course (Statistical Machine Learning).

Here we focus mainly on discrete domains that allow convenient symbolic representations. Typically:

- Instance attributes are Boolean values;
- Hypotheses are logical formulas.

Symbolic representations have the advantage of *understandability* to a human. Important e.g. in medical applications.

Currently studied in the field of “Explainable AI”.

A *learning model* is an abstract description of real-life machine-learning scenarios. It defines

- The learner-environment interaction protocol
- How learning examples are conveyed to the learner
- What properties the examples must possess
- What it means to learn successfully

We will discuss two learning models:

- *Mistake Bound Learning*
- *Probably Approximately Correct Learning*.

Sometimes, *hypotheses* are also called *models* but here we mean a *model of learning*.

Mistake Bound Model

A very simple model assuming an *online* interaction: a concept C is chosen from a fixed concept class and the following is then repeated indefinitely:

- 1 The learner receives an example $x \in X$
- 2 It predicts whether x is positive ($x \in C$) or negative ($x \notin C$)
- 3 It is told the correct answer (so it can adapt after a wrong prediction)

To define the model, we assume there is a measure n of *instance complexity*. When X consists of fixed-arity tuples, we set $n =$ their arity.

Denote $\text{poly}(n)$ to mean “at most polynomial in n ”.

In math expressions, $f(n) \leq \text{poly}(n)$ means that $f(n)$ grows at most polynomially.

Mistake Bound Model

We say that an algorithm *learns concept class* \mathcal{C} if for any $C \in \mathcal{C}$, the number of mistakes it makes is $\text{poly}(n)$; if such an algorithm exists, \mathcal{C} is called *learnable* in the mistake bound model.

We will omit “in the mistake bound model” in this section.

Note that the learner

- cannot assume anything about the choice of examples (no i.i.d. or order assumption etc.);
- which learns \mathcal{C} stops making mistakes after a finite number of decisions.

If an algorithm learns \mathcal{C} and the maximum time it uses to process a single example is also $\text{poly}(n)$, we say it learns \mathcal{C} *efficiently* and we call \mathcal{C} *efficiently learnable*.

Learning Conjunctions

Assume $X = \{0, 1\}^n$ ($n \in \mathbb{N}$) and \mathcal{C} consists of all concepts expressible via conjunctions on n variables. Consider the following *generalization* algorithm.

- 1 Initial hypothesis $h = h_1 \overline{h_1} h_2 \overline{h_2} \dots h_n \overline{h_n}$
- 2 Receive example x , decide “yes” iff h true for x ($x \models h$)
- 3 If decision was “no” and was wrong, remove all h 's literals false for x
- 4 If decision was “yes” and was wrong, output “Concept cannot be described by a conjunction.”
- 5 Go to 2

To adapt this algo for $\mathcal{C} =$ *monotone conjunctions* (conj. with no negations), use $h = h_1 h_2 \dots h_n$ in Step 1.

Learning Conjunctions

Let $C \in \mathcal{C}$ be the concept used to generate the examples and c the conjunction that encodes it. Observe and explain why:

- Initial h tautologically false, n literals get deleted from it on first mistake on a positive (in-concept) example, resulting in $|h| = n$.
- If a literal is in c , it is never deleted from h , so $c \subseteq h$ (literal-wise).
- At least one literal is deleted on each mistake.
- So the max number of mistakes is $n + 1 \leq \text{poly}(n)$.

Thus the algorithm learns conjunctions (in the MB model) and does so efficiently (time per example is linear in n).

So *conjunctions are efficiently learnable*.

Learning Disjunctions

Efficient learnability of conjunctions implies the same for *disjunctions*.

If disjunction c defines concept C then \bar{c} is a *conjunction* defining the *complementary* concept $X \setminus C$.

Use any efficient conjunction learner to learn $X \setminus C$, so the correct answers provided to the learner are according to \bar{c} .

Then negate the hypothesis returned by the algorithm, obtaining a disjunction for C .

Learning k -CNF and k -DNF

k -CNF (DNF) is the class of CNF (DNF) formulas whose clauses (terms) have at most k literals. For example, 3-CNF includes

$$(a \vee b)(b \vee \bar{c} \vee d)$$

k -CNF is efficiently learnable.

With n variables, there are $n' = \sum_{i=1}^k \binom{n}{i} 2^i \leq \text{poly}(n)$ different clauses.

Introduce a new variable for each of the n' clauses and use an efficient learner to learn a monotone conjunction on these variables. Then plug the original clauses for the variables in the resulting conjunction, obtaining a k -CNF formula. This is efficient due to $n' \leq \text{poly}(n)$.

Analogously, also *k -DNF is efficiently learnable.*

Learning k -term DNF and k -clause CNF

k -term DNF (k -clause CNF): at most k terms (clauses).

No algorithm known for efficient learning of k -term DNF using k -term DNF as the hypothesis class. Same for k -clause CNF.

But k -term DNF \subseteq k -CNF since any k -term DNF can be written as an equivalent k -CNF by “multiplying-out.” E.g.,

$$(abc) \vee (de) \equiv (a \vee d)(a \vee e)(b \vee d)(b \vee e)(c \vee d)(c \vee e)$$

So k -term DNF is efficiently learnable by an algorithm using k -CNF as its hypothesis class. This is called *improper* learning.

Analogously: k -clause CNF learnable using k -DNF.